

Optimization problems of a microalgal raceway to enhance productivity

Olivier Bernard, Liudi LU, Jacques Sainte-Marie, Julien Salomon

November 4, 2020

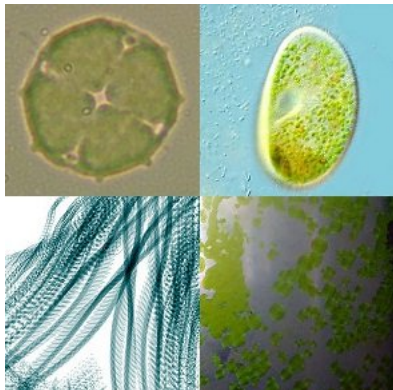
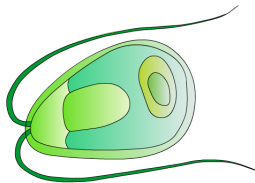
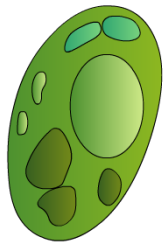
- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem
- 4 Numerical Experiments
- 5 Conclusion and Perspective

- Who?

- Who? Microalgae

- Who? Microalgae: photosynthetic organisms

Introduction



- Who? Microalgae: photosynthetic organisms
- Why?

- Who? Microalgae: photosynthetic organisms
- Why? Biotechnological potential

- Who? Microalgae: photosynthetic organisms
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc

- Who? Microalgae: photosynthetic organisms
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc
- Where?

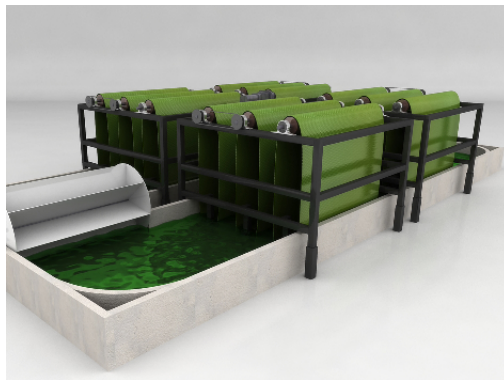
- Who? Microalgae: photosynthetic organisms
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc
- Where?
 - All aquatic environments

- Who? Microalgae: photosynthetic organisms
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc
- Where?
 - All aquatic environments
 - Industrial cultivation - photobioreactors: Chemostats, RAB, Raceways, etc

Introduction



Introduction



Introduction



- 1 Introduction
- 2 Raceway Modeling
 - Hydrodynamic model
 - Light intensity
 - Biologic model
 - Mixing device
- 3 Optimization problem
- 4 Numerical Experiments
- 5 Conclusion and Perspective

- 1D steady state shallow water equation

$$\partial_x(hu) = 0, \quad (1)$$

$$\partial_x\left(hu^2 + g\frac{h^2}{2}\right) = -gh\partial_x z_b. \quad (2)$$

Shallow Water Equations

- 1D steady state shallow water equation

$$\partial_x(hu) = 0, \quad (1)$$

$$\partial_x\left(hu^2 + g\frac{h^2}{2}\right) = -gh\partial_x z_b. \quad (2)$$

- h water elevation, u horizontal averaged velocity, g gravitational acceleration, z_b topography.

Shallow Water Equations

- 1D steady state shallow water equation

$$\partial_x(hu) = 0, \quad (1)$$

$$\partial_x\left(hu^2 + g\frac{h^2}{2}\right) = -gh\partial_x z_b. \quad (2)$$

- h water elevation, u horizontal averaged velocity, g gravitational acceleration, z_b topography.
- Free surface $\eta := h + z_b$, averaged discharge $Q = hu$.

Shallow Water Equations

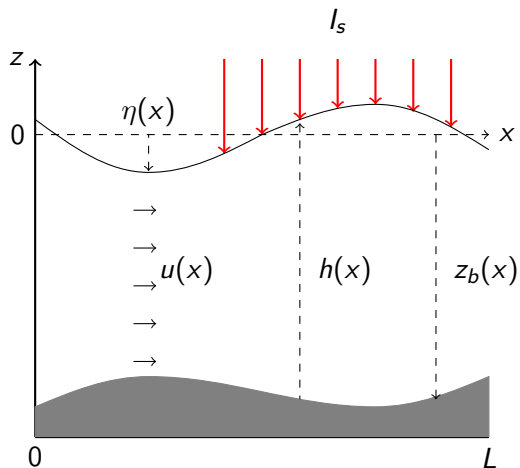


Figure: Representation of the hydrodynamic model.

1D steady state shallow water equation

$$\partial_x(hu) = 0, \quad (1)$$

$$\partial_x\left(hu^2 + g\frac{h^2}{2}\right) = -gh\partial_x z_b. \quad (2)$$

Shallow Water Equations

Integrating (1)

$$hu = Q_0,$$

for a fixed positive constant Q_0 .

Shallow Water Equations

$$hu = Q_0 \quad (1)$$

$$\partial_x(hu^2 + g\frac{h^2}{2}) = -gh\partial_x z_b. \quad (2)$$

Shallow Water Equations

$$hu = Q_0 \quad (1)$$

$$hu\partial_x u + h\partial_x gh + h\partial_x gz_b = 0 \quad (2)$$

Assume $h > 0$ and $Q_0 > 0$

Shallow Water Equations

$$hu = Q_0 \quad (1)$$

$$\partial_x \left(\frac{Q_0^2}{2h^2} + g(h + z_b) \right) = 0 \quad (2)$$

Consider two fixed constants $h(0), z_b(0) \in \mathbb{R}$

Shallow Water Equations

$$hu = Q_0 \tag{1}$$

$$\frac{Q_0^2}{2h^2} + g(h + z_b) = \frac{Q_0^2}{2h^2(0)} + g(h(0) + z_b(0)) =: M_0 \tag{2}$$

Consider two fixed constants $h(0), z_b(0) \in \mathbb{R}$

Shallow Water Equations

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

Shallow Water Equations

- u, z_b as a function of h

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

Shallow Water Equations

- u, z_b as a function of h

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

- Froude number:

$$Fr := \frac{u}{\sqrt{gh}}$$

$Fr < 1$: subcritical case (i.e. the flow regime is fluvial)

$Fr > 1$: supercritical case (i.e. the flow regime is torrential)

Shallow Water Equations

- u, z_b as a function of h

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

- Froude number:

$$Fr := \frac{u}{\sqrt{gh}}$$

$Fr < 1$: subcritical case (i.e. the flow regime is fluvial)

$Fr > 1$: supercritical case (i.e. the flow regime is torrential)

- Given a smooth topography z_b , there exists a unique positive smooth solution of h which satisfies the subcritical flow condition [4, Lemma 1]

- Incompressibility of the flow: $\nabla \cdot \underline{\mathbf{u}} = 0$ with $\underline{\mathbf{u}} = (u(x), w(x, z))$

$$\partial_x u + \partial_z w = 0. \quad (3)$$

- Integrating (3) from z_b to z gives:

$$\begin{aligned}0 &= \int_{z_b}^z (\partial_x u(x) + \partial_z w(x, z)) dz \\ &= \partial_x \int_{z_b}^z u(x) dz + \int_{z_b}^z \partial_z w(x, z) dz \\ &= \partial_x ((z - z_b)u(x)) + w(x, z) - w(x, z_b) \\ &= (z - z_b)\partial_x u(x) - u(x)\partial_x z_b + w(x, z),\end{aligned}$$

where $w(x, z_b) = u(x)\partial_x z_b$ (the kinematic condition at the bottom).

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- The Lagrangian trajectory is characterized by the system

$$\begin{pmatrix} \dot{x}(t) \\ \dot{z}(t) \end{pmatrix} = \begin{pmatrix} u(x(t)) \\ w(x(t), z(t)) \end{pmatrix}.$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

-

$$z' := \frac{\dot{z}}{\dot{x}} = \left(\frac{M_0}{g} - \frac{3u^2}{2g} - z \right) \frac{u'}{u}.$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- Recall $\eta = h + z_b = \frac{M_0}{g} - \frac{u^2}{2g}$

$$\begin{aligned} z' + z \frac{u'}{u} &= \left(\frac{M_0}{g} - \frac{3u^2}{2g} \right) \frac{u'}{u} \\ &= \left(\eta + \frac{u^2}{g} \right) \frac{u'}{u}. \end{aligned}$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- Note that $\eta' = -\frac{uu'}{g}$ and multiplying both sides by u

$$\begin{aligned} z'u + zu' &= \eta u' + \frac{u^2}{g} u' \\ &= \eta u' + \eta' u \end{aligned}$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- We find

$$(u(z - \eta))' = 0$$

Since $h(0)$, $z_b(0)$ are given constants, so does $u(0)$. For a given initial position $z(0)$, we have

$$u(x)(z(x) - \eta(x)) = u(0)(z(0) - \eta(0)).$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- A time-free reformulation for z as

$$z(x) = \eta(x) + \frac{u(0)}{u(x)} (z(0) - \eta(0)), \quad (3)$$

- The vertical velocity:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x).$$

- A time-free reformulation for z as

$$z(x) = \eta(x) + \frac{u(0)}{u(x)}(z(0) - \eta(0)), \quad (3)$$

- If $z(0)$ belongs to $[z_b(0), \eta(0)]$, then $z(x)$ belongs to $[z_b(x), \eta(x)]$. In particular, choosing $z(0) = z_b(0)$ in (3) and using (1) gives $z(x) = z_b(x)$. In the same way, we find that $z(x) = \eta(x)$ when $z(0) = \eta(0)$.

- The Beer-Lambert law describes how light is attenuated with depth:

$$I(x, z) = I_s \exp \left(- \varepsilon(\eta(x) - z) \right).$$

Here ε is the light extinction coefficient.

- The Beer-Lambert law describes how light is attenuated with depth:

$$I(x, z(0)) = I_s \exp \left(-\varepsilon \frac{u(0)}{u(x)} (\eta(0) - z(0)) \right).$$

Here ε is the light extinction coefficient.

- The Beer-Lambert law describes how light is attenuated with depth:

$$I(x, z(0)) = I_s \exp \left(-\varepsilon \frac{u(0)}{u(x)} (\eta(0) - z(0)) \right).$$

Here ε is the light extinction coefficient.

-

$$h \rightarrow u, z_b \rightarrow z \rightarrow I$$

- *A*: open and ready to harvest a photon,
B: closed while processing the absorbed photon energy,
C: inhibited if several photons have been absorbed simultaneously.

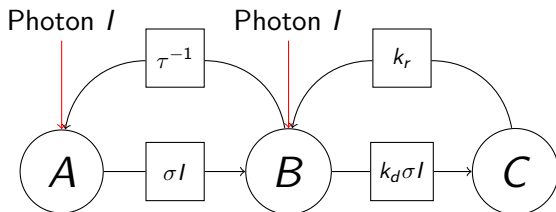


Figure: Scheme of the Han model, representing the probability of state transition, as a function of the photon flux density.

- A : open and ready to harvest a photon,
 B : closed while processing the absorbed photon energy,
 C : inhibited if several photons have been absorbed simultaneously.

-

$$\begin{cases} \dot{A} = -\sigma IA + \frac{B}{\tau}, \\ \dot{B} = \sigma IA - \frac{B}{\tau} + k_r C - k_d \sigma IB, \\ \dot{C} = -k_r C + k_d \sigma IB. \end{cases}$$

- A : open and ready to harvest a photon,
 B : closed while processing the absorbed photon energy,
 C : inhibited if several photons have been absorbed simultaneously.

-

$$\begin{cases} \dot{A} = -\sigma IA + \frac{B}{\tau}, \\ \dot{B} = \sigma IA - \frac{B}{\tau} + k_r C - k_d \sigma IB, \\ \dot{C} = -k_r C + k_d \sigma IB. \end{cases}$$

- A, B, C are the relative frequencies of the three possible states

$$A + B + C = 1,$$

- Using a fast-slow approximation and the singular perturbation theory(see [3]), this system can be reduced to one single evolution equation:

$$\dot{C} = -\alpha(I)C + \beta(I),$$

where

$$\alpha(I) = \beta(I) + k_r, \text{ with } \beta(I) = k_d \tau \frac{(\sigma I)^2}{\tau \sigma I + 1}.$$

- Using a fast-slow approximation and the singular perturbation theory(see [3]), this system can be reduced to one single evolution equation:

$$\dot{C} = -\alpha(I)C + \beta(I),$$

where

$$\alpha(I) = \beta(I) + k_r, \text{ with } \beta(I) = k_d \tau \frac{(\sigma I)^2}{\tau \sigma I + 1}.$$

- The net specific growth rate:

$$\mu(C, I) := -\gamma(I)C + \zeta(I),$$

where

$$\zeta(I) = \gamma(I) - R, \text{ with } \gamma(I) = \frac{k\sigma I}{\tau \sigma I + 1}.$$

- A time-free reformulation of C

$$C' := \frac{\dot{C}}{\dot{x}} = -\frac{\alpha(I)}{u}C + \frac{\beta(I)}{u},$$

- A time-free reformulation of C

$$C' := \frac{\dot{C}}{\dot{x}} = -\frac{\alpha(I)}{u}C + \frac{\beta(I)}{u},$$

- The average net specific growth rate over the domain is defined by

$$\bar{\mu} := \frac{1}{L} \int_0^L \frac{1}{h(x)} \int_{z_b(x)}^{\eta(x)} \mu(C(x, z), I(x, z)) dz dx.$$

- A time-free reformulation of C

$$C' := \frac{\dot{C}}{\dot{x}} = -\frac{\alpha(I)}{u}C + \frac{\beta(I)}{u},$$

- The average net specific growth rate over the domain is defined by

$$\bar{\mu} := \frac{1}{L} \int_0^L \frac{1}{h(x)} \int_{z_b(x)}^{\eta(x)} \mu(C(x, z), I(x, z)) dz dx.$$

- In order to compute numerically, consider a uniform vertical discretization of the initial position $z(0)$ for $N_z + 1$ cells:

$$z_i(0) = \eta(0) - \frac{i-1}{N_z} h(0), \quad i = 1, \dots, N_z + 1.$$

- A time-free reformulation of C

$$C' := \frac{\dot{C}}{\dot{x}} = -\frac{\alpha(I)}{u}C + \frac{\beta(I)}{u},$$

- The average net specific growth rate over the domain is defined by

$$\bar{\mu} := \frac{1}{L} \int_0^L \frac{1}{h(x)} \int_{z_b(x)}^{\eta(x)} \mu(C(x, z), I(x, z)) dz dx.$$

- In order to compute numerically, consider a uniform vertical discretization of the initial position $z(0)$ for $N_z + 1$ cells:

$$z_i(0) = \eta(0) - \frac{i-1}{N_z} h(0), \quad i = 1, \dots, N_z + 1.$$

- The semi-discrete average net specific growth rate:

$$\bar{\mu}_\Delta = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \mu(C_i(x), I_i(x)) dx. \quad (4)$$

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.
- An ideal rearrangement of trajectories: at each new lap, the algae at depth $z_i(0)$ are entirely transferred into the position $z_j(0)$ when passing through the mixing device.

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.
- An ideal rearrangement of trajectories: at each new lap, the algae at depth $z_i(0)$ are entirely transferred into the position $z_j(0)$ when passing through the mixing device.
- We denote by \mathcal{P} the set of permutation matrices of size $N_z \times N_z$ and by \mathfrak{S}_{N_z} the associated set of permutations of N_z elements.

Mixing device

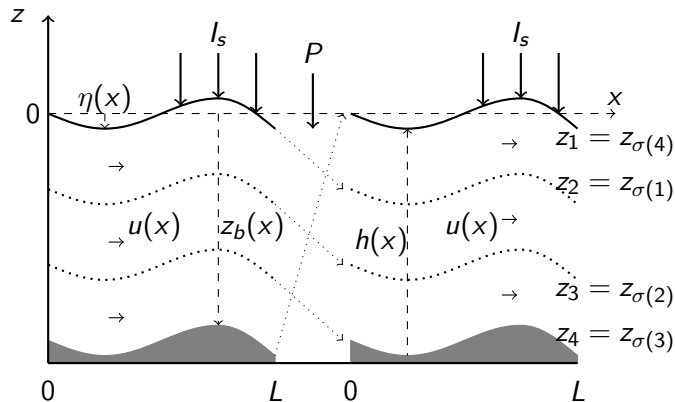


Figure: Representation of the hydrodynamic model with an example of mixing device (P). Here, P corresponds to the cyclic permutation $\sigma = (1\ 2\ 3\ 4)$.

Mixing device

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.
- An ideal rearrangement of trajectories: at each new lap, the algae at depth $z_i(0)$ are entirely transferred into the position $z_j(0)$ when passing through the mixing device.
- We denote by \mathcal{P} the set of permutation matrices of size $N_z \times N_z$ and by \mathfrak{S}_{N_z} the associated set of permutations of N_z elements.

Theorem

The average growth rate of K laps equals to one lap (see [1]).

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem**
 - ε constant and no permutation
 - ε constant with mixing device
- 4 Numerical Experiments
- 5 Conclusion and Perspective

Optimization problem

- Volume of the system

$$V = \int_0^L h(x) dx.$$

Optimization problem

- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.

Optimization problem

- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.
- For instance: a truncated Fourier series

$$h(x, a) = a_0 + \sum_{m=1}^M a_m \sin\left(2m\pi \frac{x}{L}\right), \quad (5)$$

Optimization problem

- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.
- For instance: a truncated Fourier series

$$h(x, a) = a_0 + \sum_{m=1}^M a_m \sin(2m\pi \frac{x}{L}), \quad (5)$$

- $a \rightarrow h \rightarrow u, z_b \rightarrow z \rightarrow I \rightarrow C \rightarrow \mu$ or $\bar{\mu}$.

Optimization problem

- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.
- For instance: a truncated Fourier series

$$h(x, a) = a_0 + \sum_{m=1}^M a_m \sin(2m\pi \frac{x}{L}), \quad (5)$$

- $a \rightarrow h \rightarrow u, z_b \rightarrow z \rightarrow I \rightarrow C \rightarrow \mu$ or $\bar{\mu}$.
- Periodic of C .

Optimization problem

- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.
- For instance: a truncated Fourier series

$$h(x, a) = a_0 + \sum_{m=1}^M a_m \sin(2m\pi \frac{x}{L}), \quad (5)$$

- $a \rightarrow h \rightarrow u, z_b \rightarrow z \rightarrow I \rightarrow C \rightarrow \mu$ or $\bar{\mu}$.
- Periodic of C .
- Omit x in notations.

- Objective function:

$$\bar{\mu}_{\Delta}(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i + \zeta(l_i(a))}{u(a)} dx,$$

- Objective function:

$$\bar{\mu}_{\Delta}(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i + \zeta(l_i(a))}{u(a)} dx,$$

- Constraints:

$$C_i' + \frac{\alpha(l_i(a))}{u(a)} C_i = \frac{\beta(l_i(a))}{u(a)}. \quad (6)$$

- Objective function:

$$\bar{\mu}_{\Delta}(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i + \zeta(l_i(a))}{u(a)} dx,$$

- Constraints:

$$C_i' + \frac{\alpha(l_i(a))}{u(a)} C_i = \frac{\beta(l_i(a))}{u(a)}. \quad (6)$$

- The optimization problem reads:

Find a^ solving the maximization problem:*

$$\max_{a \in \mathbb{R}^N} \bar{\mu}_{\Delta}(a).$$

- Lagrangian:

$$\begin{aligned} \mathcal{L}(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(I_i(a))C_i + \zeta(I_i(a))}{u(a)} dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \left(C_i' + \frac{\alpha(I_i(a))C_i - \beta(I_i(a))}{u(a)} \right) dx \end{aligned}$$

- Lagrangian:

$$\begin{aligned}\mathcal{L}(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(I_i(a))C_i + \zeta(I_i(a))}{u(a)} dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \left(C_i' + \frac{\alpha(I_i(a))C_i - \beta(I_i(a))}{u(a)} \right) dx\end{aligned}$$

- p_i the Lagrange multipliers associated with the constraint (6).

$$\begin{cases} \partial_{C_i} \mathcal{L} = p_i' - p_i \frac{\alpha(I_i(a))}{u(a)} - \frac{1}{LN_z} \frac{\gamma(I_i(a))}{u(a)} \\ \partial_{C_i(L)} \mathcal{L} = p_i(L). \end{cases}$$

- Lagrangian:

$$\begin{aligned}\mathcal{L}(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(I_i(a))C_i + \zeta(I_i(a))}{u(a)} dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \left(C_i' + \frac{\alpha(I_i(a))C_i - \beta(I_i(a))}{u(a)} \right) dx\end{aligned}$$

- p_i the Lagrange multipliers associated with the constraint (6).

$$\begin{cases} \partial_{C_i} \mathcal{L} = p_i' - p_i \frac{\alpha(I_i(a))}{u(a)} - \frac{1}{LN_z} \frac{\gamma(I_i(a))}{u(a)} \\ \partial_{C_i(L)} \mathcal{L} = p_i(L). \end{cases}$$

- If C is periodic (i.e. $C(0) = C(L)$), then $\partial_{C_i(L)} \mathcal{L} = p_i(L) - p_i(0)$.

ε constant and no permutation

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

- where

$$\begin{aligned} \partial_a \mathcal{L} = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma'(l_i(a))C_i + \zeta'(l_i(a))}{u(a)} \partial_a l_i(a) dx \\ & - \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i + \zeta(l_i(a))}{u^2(a)} \partial_a u(a) dx \\ & + \sum_{i=1}^{N_z} \int_0^L p_i \frac{-\alpha'(l_i(a))C_i + \beta'(l_i(a))}{u(a)} \partial_a l_i(a) dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \frac{-\alpha(l_i(a))C_i + \beta(l_i(a))}{u^2(a)} \partial_a u(a) dx. \end{aligned}$$

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

Theorem

Under the parameterization (5), if C is periodic, then $\nabla \bar{\mu}_\Delta(0) = 0$.

- Objective function:

$$\bar{\mu}_{\Delta}^P(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i^P + \zeta(l_i(a))}{u(a)} dx,$$

- Objective function:

$$\bar{\mu}_{\Delta}^P(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i^P + \zeta(l_i(a))}{u(a)} dx,$$

- Constraint:

$$\begin{cases} C_i^{P'} + \frac{\alpha(l_i(a))}{u(a)} C_i^P & = \frac{\beta(l_i(a))}{u(a)} \\ P C_i^P(L) & = C_i^P(0). \end{cases} \quad (7)$$

- Objective function:

$$\bar{\mu}_{\Delta}^P(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i^P + \zeta(l_i(a))}{u(a)} dx,$$

- Constraint:

$$\begin{cases} C_i^{P'} + \frac{\alpha(l_i(a))}{u(a)} C_i^P & = \frac{\beta(l_i(a))}{u(a)} \\ P C_i^P(L) & = C_i^P(0). \end{cases} \quad (7)$$

- Our optimization problem reads:

Find a permutation matrix P_{\max} and a parameter vector a^ solving the maximization problem:*

$$\max_{P \in \mathcal{P}} \max_{a \in \mathbb{R}^M} \bar{\mu}_{\Delta}^P(a).$$

- Lagrangian:

$$\begin{aligned} \mathcal{L}^P(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i^P + \zeta(l_i(a))}{u(a)} dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i^P \left(C_i^{P'} + \frac{\alpha(l_i(a))C_i^P - \beta(l_i(a))}{u(a)} \right) dx \end{aligned}$$

- Lagrangian:

$$\begin{aligned} \mathcal{L}^P(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_i^P + \zeta(l_i(a))}{u(a)} dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i^P \left(C_i^{P'} + \frac{\alpha(l_i(a))C_i^P - \beta(l_i(a))}{u(a)} \right) dx \end{aligned}$$

- p_i^P is the Lagrange multiplier associated with the constraint (7).

$$\begin{cases} p_i^{P'} - p_i^P \frac{\alpha(l_i(a))}{u(a)} - \frac{1}{LN_z} \frac{\gamma(l_i(a))}{u(a)} & = 0 \\ p_i^P(L) - p_i^P(0)P & = 0. \end{cases}$$

$$\nabla \bar{\mu}_{\Delta}^P(a) = \partial_a \mathcal{L}^P,$$

where

$$\begin{aligned} \partial_a \mathcal{L}^P &= \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma'(l_i(a))C_i^P + \zeta'(l_i(a))}{u(a)} \partial_a l_i(a) dx \\ &\quad - \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \frac{-\gamma(l_i(a))C_n^P + \zeta(l_i(a))}{u^2(a)} \partial_a u(a) dx \\ &\quad + \sum_{i=1}^{N_z} \int_0^L p_i^P \frac{-\alpha'(l_i(a))C_i^P + \beta'(l_i(a))}{u(a)} \partial_a l_i(a) dx \\ &\quad - \sum_{i=1}^{N_z} \int_0^L p_i^P \frac{-\alpha(l_i(a))C_i^P + \beta(l_i(a))}{u^2(a)} \partial_a u(a) dx. \end{aligned}$$

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem
- 4 Numerical Experiments**
 - Numerical Settings
 - Numerical results
- 5 Conclusion and Perspective

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc
- The spatial increment: $\Delta x = 0.01$ m

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc
- The spatial increment: $\Delta x = 0.01 \text{ m}$
- Light intensity at free surface: $I_s = 2000 \mu\text{molm}^{-2} \text{ s}^{-1}$ (which corresponds to a maximum value during summer in the south of France).

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc
- The spatial increment: $\Delta x = 0.01 \text{ m}$
- Light intensity at free surface: $I_s = 2000 \mu\text{molm}^{-2} \text{ s}^{-1}$ (which corresponds to a maximum value during summer in the south of France).
- Assume that only q percent of I_s is available at the bottom $q \in [0, 1]$

$$\varepsilon = (1/h(0, a)) \ln(1/q).$$

Parameter Settings

- The spatial increment: $\Delta x = 0.01$ m

Parameter Settings

- The spatial increment: $\Delta x = 0.01 \text{ m}$
- Standard settings for a raceway pond
 - Length of one lap of the raceway $L = 100 \text{ m}$
 - Averaged discharge $Q_0 = 0.04 \text{ m}^2 \cdot \text{s}^{-1}$
 - Initial position of the topography $z_b(0) = -0.4 \text{ m}$
 - First Fourier coefficient $a_0 = 0.4$

Parameter Settings

- The spatial increment: $\Delta x = 0.01 \text{ m}$
- Standard settings for a raceway pond
 - Length of one lap of the raceway $L = 100 \text{ m}$
 - Averaged discharge $Q_0 = 0.04 \text{ m}^2 \cdot \text{s}^{-1}$
 - Initial position of the topography $z_b(0) = -0.4 \text{ m}$
 - First Fourier coefficient $a_0 = 0.4$
- The free-fall acceleration is set to be $g = 9.81 \text{ m} \cdot \text{s}^{-2}$.

Parameter Settings

- The spatial increment: $\Delta x = 0.01$ m
- Standard settings for a raceway pond
 - Length of one lap of the raceway $L = 100$ m
 - Averaged discharge $Q_0 = 0.04 \text{ m}^2 \cdot \text{s}^{-1}$
 - Initial position of the topography $z_b(0) = -0.4$ m
 - First Fourier coefficient $a_0 = 0.4$
- The free-fall acceleration is set to be $g = 9.81 \text{ m} \cdot \text{s}^{-2}$.
- All the numerical parameters values for Han's model are taken from [2] and given in table 1.

Table: Parameter values for Han Model

k_r	$6.8 \cdot 10^{-3}$	s^{-1}
k_d	$2.99 \cdot 10^{-4}$	-
τ	0.25	s
σ	0.047	$\text{m}^2 \cdot (\mu \text{ mol})^{-1}$
k	$8.7 \cdot 10^{-6}$	-
R	$1.389 \cdot 10^{-7}$	s^{-1}

Convergence of N_z

For 100 random a chosen, the average value of the functional $\bar{\mu}_\Delta$

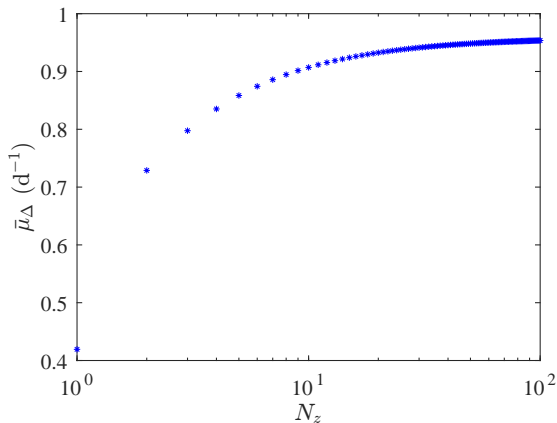


Figure: The value of the functional $\bar{\mu}_\Delta$ for $N_z = [1, 100]$.

C no periodic

The initial condition $C_0 = 0.1$

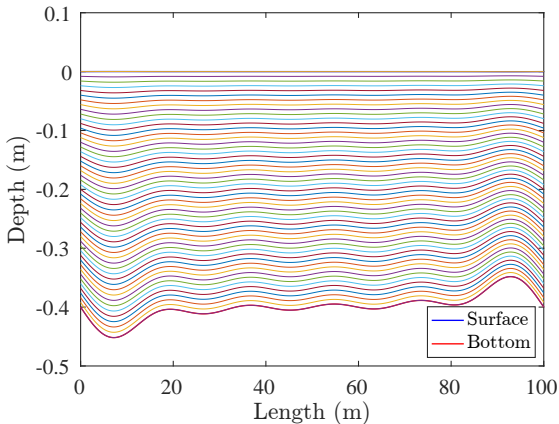


Figure: The optimal topography for $C_0 = 0.1$. The red thick line represents the topography (z_b), the blue thick line represents the free surface (η), and all the other curves between represent the different trajectories.

Optimal topography for a given permutation

The permutation: $\pi = (1 N_z)(2 N_z - 1)(3 N_z - 2) \cdots$,

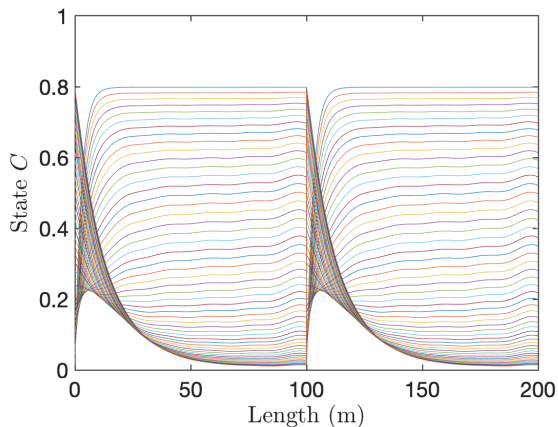
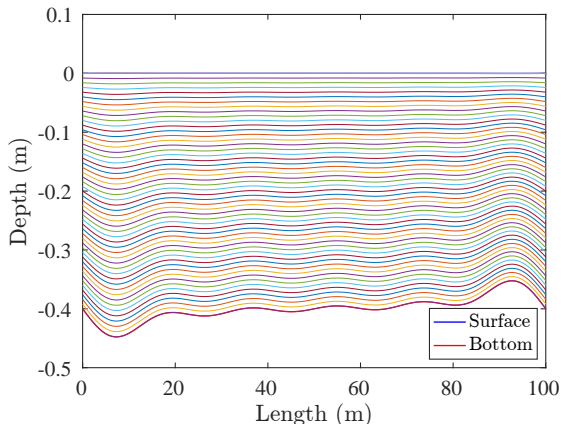


Figure: The evolution of the photo-inhibition state C for two laps.

Optimal topography for a given permutation

The permutation: $\pi = (1 N_z)(2 N_z - 1)(3 N_z - 2) \dots$,



The increase in the optimal value of the objective function $\bar{\mu}_\Delta$ compared to a flat topography is around 0.228%, and compare to a flat topography and non permutation case is around 0.277%.

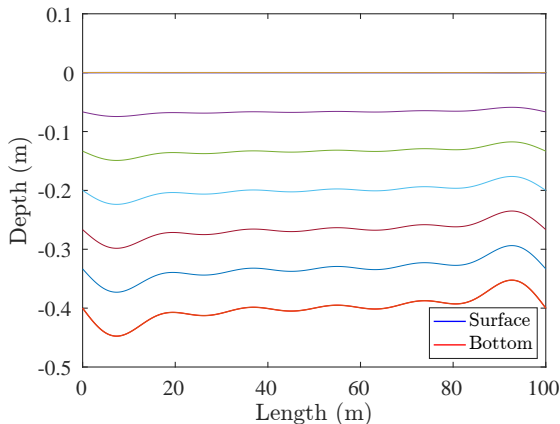
Optimal matrix and optimal topography

Set $N_z = 7$, the optimal matrix:

$$P_{\max} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Optimal matrix and optimal topography

Set $N_z = 7$, the optimal topography:



Compare to a flat topography with this P_{\max} , we have a gain of 0.224%, and a gain of 1.511% compare to the case a flat topography without permutation (i.e. \mathcal{I}_{N_z}).

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem
- 4 Numerical Experiments
- 5 Conclusion and Perspective**

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution
 - A non flat topography slightly enhances the average growth rate

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate
- Perspectives
 - More general matrix P

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate
- Perspectives
 - More general matrix P
 - What happens in the case torrential

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate
- Perspectives
 - More general matrix P
 - What happens in the case torrential
 - An extra diffusion term in Shallow water equations or a Brownian in Lagrangian trajectories

Permutation for flat topography

- Flat topography $\rightarrow h, u, z_b$ constants $\rightarrow z$ constant $\rightarrow l$ constant

Permutation for flat topography

- Flat topography $\rightarrow h, u, z_b$ constants $\rightarrow z$ constant $\rightarrow l$ constant
- C can be computed explicitly

Permutation for flat topography

- Flat topography $\rightarrow h, u, z_b$ constants $\rightarrow z$ constant $\rightarrow l$ constant
- C can be computed explicitly
- μ can be computed explicitly

Permutation for flat topography

- Flat topography $\rightarrow h, u, z_b$ constants $\rightarrow z$ constant $\rightarrow l$ constant
- C can be computed explicitly
- μ can be computed explicitly

$$\bar{\mu}_\Delta = \frac{1}{N_z} \frac{1}{T} \left(\langle \Gamma, C(0) \rangle + \langle \mathbf{1}, Z \rangle \right),$$

- $\mathbf{1}$ is a vector of size N_z whose coefficients equal 1
- $\Gamma_i = \frac{\gamma(l_i)}{\alpha(l_i)} (e^{-\alpha(l_i)T} - 1)$
- $Z_i = \frac{\gamma(l_i)}{\alpha(l_i)} \frac{\beta(l_i)}{\alpha(l_i)} (1 - e^{-\alpha(l_i)T}) - \frac{\gamma(l_i)\beta(l_i)}{\alpha(l_i)} T + \zeta(l_i)T$

Permutation for flat topography

- Flat topography $\rightarrow h, u, z_b$ constants $\rightarrow z$ constant $\rightarrow l$ constant
- C can be computed explicitly
- μ can be computed explicitly

$$\bar{\mu}_\Delta = \frac{1}{N_z} \frac{1}{T} \left(\langle \Gamma, C(0) \rangle + \langle \mathbf{1}, Z \rangle \right),$$

- $\mathbf{1}$ is a vector of size N_z whose coefficients equal 1
- $\Gamma_i = \frac{\gamma(l_i)}{\alpha(l_i)} (e^{-\alpha(l_i)T} - 1)$
- $Z_i = \frac{\gamma(l_i)}{\alpha(l_i)} \frac{\beta(l_i)}{\alpha(l_i)} (1 - e^{-\alpha(l_i)T}) - \frac{\gamma(l_i)\beta(l_i)}{\alpha(l_i)} T + \zeta(l_i)T$
- The periodic condition of C

$$C(0) = (\mathcal{I}_{N_z} - PD)^{-1}PV.$$

- D is a diagonal matrix $D_{ii} = e^{-\alpha(l_i)T}$
- $V_i = \frac{\beta(l_i)}{\alpha(l_i)} (1 - e^{-\alpha(l_i)T})$

Permutation for flat topography

- Since N , T and Z are independent of P , the objective function defined by

$$J(P) = \langle \Gamma, (\mathcal{I}_{N_z} - PD)^{-1}PV \rangle.$$

Permutation for flat topography

- Since N , T and Z are independent of P , the objective function defined by

$$J(P) = \langle \Gamma, (\mathcal{I}_{N_z} - PD)^{-1}PV \rangle.$$

- The optimization problem then reads:
Find a permutation matrix P_{\max} solving the maximization problem:

$$\max_{P \in \mathcal{P}} J(P).$$

Permutation for flat topography

- Since N , T and Z are independent of P , the objective function defined by

$$J(P) = \langle \Gamma, (\mathcal{I}_{N_z} - PD)^{-1}PV \rangle.$$

- The optimization problem then reads:
Find a permutation matrix P_{\max} solving the maximization problem:

$$\max_{P \in \mathcal{P}} J(P).$$

- Expansion of $J(P)$

$$\begin{aligned} \langle \Gamma, (\mathcal{I}_{N_z} - PD)^{-1}PV \rangle &= \sum_{m=0}^{+\infty} \langle \Gamma, (PD)^m PV \rangle \\ &= \langle \Gamma, PV \rangle + \sum_{m=1}^{+\infty} \langle \Gamma, (PD)^m PV \rangle. \end{aligned}$$

Permutation for flat topography

- Since N , T and Z are independent of P , the objective function defined by

$$J(P) = \langle \Gamma, (\mathcal{I}_{N_z} - PD)^{-1}PV \rangle.$$

- The optimization problem then reads:
Find a permutation matrix P_{\max} solving the maximization problem:

$$\max_{P \in \mathcal{P}} J(P).$$

- Approximation

$$J^{\text{approx}}(P) = \langle \Gamma, PV \rangle.$$

Permutation for flat topography

- Since N , T and Z are independent of P , the objective function defined by

$$J(P) = \langle \Gamma, (\mathcal{I}_{N_z} - PD)^{-1}PV \rangle.$$

- The optimization problem then reads:
Find a permutation matrix P_{\max} solving the maximization problem:

$$\max_{P \in \mathcal{P}} J(P).$$

- Approximation

$$J^{\text{approx}}(P) = \langle \Gamma, PV \rangle.$$

- The optimal solution P_{\max}^{approx} of $J^{\text{approx}}(P)$ can be determined explicitly as the matrix corresponding to the permutation which associates the largest element of Γ with the largest element of V , the second largest element with the second largest, and so on.

Possible permutation

- Set $T = 1000$ s, $q = 10\%$, $P_{\max} = \mathcal{I}_{N_z}$.

Possible permutation

- Set $T = 1000$ s, $q = 10\%$, $P_{\max} = \mathcal{I}_{N_z}$.
- Set $T = 1000$ s, $q = 1\%$

$$P_{\max} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

Possible permutation

- Set $T = 1000$ s, $q = 0.1\%$

$$P_{\max} = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} .$$

Possible permutation

- Set $T = 1000$ s, $q = 0.1\%$

$$P_{\max} = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

- For all three cases, $P_{\max}^{\text{approx}} = P_{\max}$

Possible permutation

- Set $T = 1$ s, $q = 10\%$, $P_{\max} = \mathcal{I}_{N_z}$.

Possible permutation

- Set $T = 1$ s, $q = 10\%$, $P_{\max} = \mathcal{I}_{N_z}$.
- Set $T = 1$ s, $q = 1\%$

$$P_{\max} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} .$$

Possible permutation

- Set $T = 1\text{ s}$, $q = 0.1\%$

$$P_{\max} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

Possible permutation

- Set $T = 1\text{ s}$, $q = 0.1\%$

$$P_{\max} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

- For all three cases, P_{\max}^{approx} is an anti-diagonal matrix.

Approximation

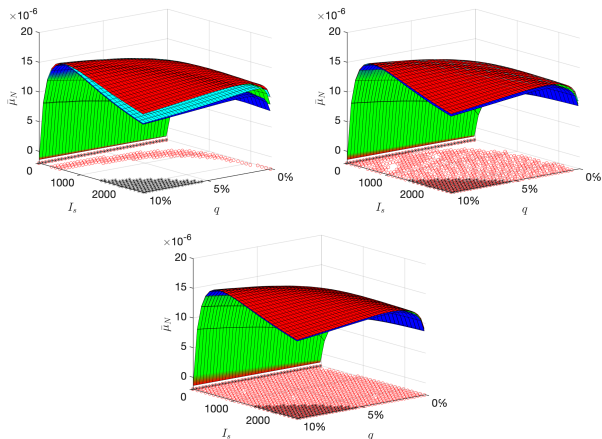


Figure: Average net specific growth rate $\bar{\mu}_N$ for $I_s \in [0, 2500]$ and $q \in [0.1\%, 10\%]$. In each figure, the red surface is obtained with P_{\max} , the dark blue surface is obtained with P_{\min} , the green surface is obtained with \mathcal{I}_{N_z} and the light blue surface is obtained with P_{\max}^{approx} . The black stars represent the cases

 Olivier Bernard, Liudi Lu, and Julien Salomon.

Optimizing microalgal productivity in raceway ponds through a controlled mixing device.

2020.

 Jérôme Grenier, F. Lopes, Hubert Bonnefond, and Olivier Bernard.

Worldwide perspectives of rotating algal biofilm up-scaling.

2020.

 Pierre-Olivier Lamare, Nina Aguillon, Jacques Sainte-Marie, Jérôme Grenier, Hubert Bonnefond, and Olivier Bernard.

Gradient-based optimization of a rotating algal biofilm process.

Automatica, 105:80–88, July 2019.

 Victor Michel-Dansac, Christophe Berthon, Stéphane Clain, and Françoise Foucher.

A well-balanced scheme for the shallow-water equations with topography.

Computers and Mathematics with Applications, 72(3):586–593, August 2016.