

Optimization problem for a microalgal raceway pond to enhance productivity

Olivier Bernard, Liu-Di LU, Jacques Sainte-Marie, Julien Salomon

December 3, 2020

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem
- 4 Numerical Experiments
- 5 Conclusion and Perspective

- Who?

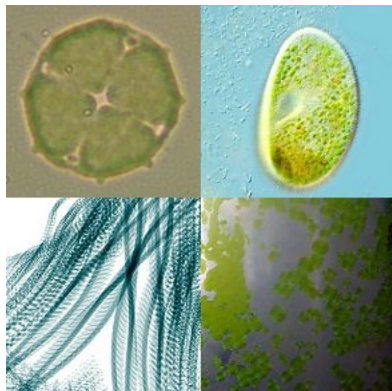
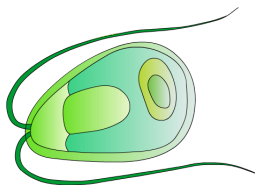
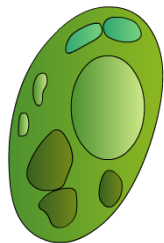


Figure: Microalgae

- Who? Microalgae
- Why?

- Who? Microalgae
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc

- Who? Microalgae
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc
- Where?

- Who? Microalgae: photosynthetic organisms
- Why? Biotechnological potential: colorants, antioxidants, cosmetics, pharmaceuticals, food complements, green energy, etc
- Where?
 - All aquatic environments
 - Industrial cultivation: photobioreactors

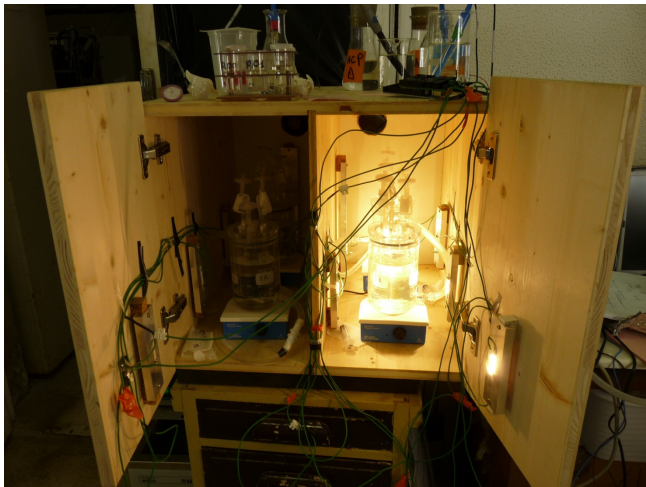


Figure: Chemostats

Introduction

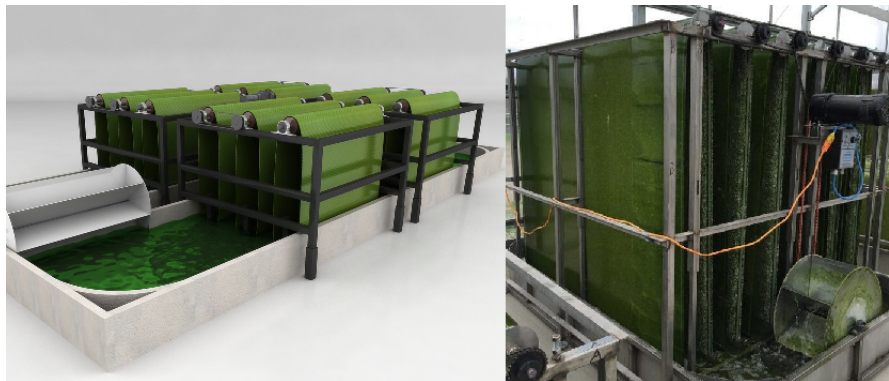


Figure: Rotating Algal Biofilm

Introduction



Figure: Raceways

- 1 Introduction
- 2 Raceway Modeling
 - Hydrodynamic model
 - Light intensity
 - Biologic model
 - Mixing device
- 3 Optimization problem
- 4 Numerical Experiments
- 5 Conclusion and Perspective

Shallow Water Equations

- 1D steady state shallow water equation

$$\partial_x(hu) = 0, \quad (1)$$

$$\partial_x\left(hu^2 + g\frac{h^2}{2}\right) = -gh\partial_x z_b. \quad (2)$$

- h water elevation, u horizontal averaged velocity, g gravitational acceleration, z_b topography.
- Free surface $\eta := h + z_b$, averaged discharge $Q = hu$.

Shallow Water Equations

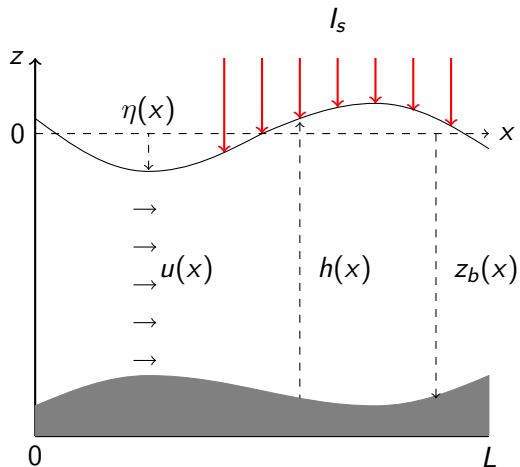


Figure: Representation of the hydrodynamic model.

Shallow Water Equations

- 1D steady state shallow water equation

$$\partial_x(hu) = 0, \quad (1)$$

$$\partial_x\left(hu^2 + g\frac{h^2}{2}\right) = -gh\partial_x z_b. \quad (2)$$

Shallow Water Equations

- u, z_b as a function of h

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

$Q_0, M_0 \in \mathbb{R}^+$ are two constants.

Shallow Water Equations

- u, z_b as a function of h

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

$Q_0, M_0 \in \mathbb{R}^+$ are two constants.

- Froude number:

$$Fr := \frac{u}{\sqrt{gh}}$$

$Fr < 1$: subcritical case (i.e. the flow regime is fluvial)

$Fr > 1$: supercritical case (i.e. the flow regime is torrential)

Shallow Water Equations

- u, z_b as a function of h

$$u = \frac{Q_0}{h}, \quad (1)$$

$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h, \quad (2)$$

$Q_0, M_0 \in \mathbb{R}^+$ are two constants.

- Froude number:

$$Fr := \frac{u}{\sqrt{gh}}$$

$Fr < 1$: subcritical case (i.e. the flow regime is fluvial)

$Fr > 1$: supercritical case (i.e. the flow regime is torrential)

- Given a smooth topography z_b , there exists a unique positive smooth solution of h which satisfies the subcritical flow condition [5, Lemma 1]

Lagrangian Trajectories

- Incompressibility of the flow: $\nabla \cdot \mathbf{u} = 0$ with $\mathbf{u} = (u(x), w(x, z))$

$$\partial_x u + \partial_z w = 0. \quad (3)$$

Lagrangian Trajectories

- Incompressibility of the flow: $\nabla \cdot \mathbf{u} = 0$ with $\mathbf{u} = (u(x), w(x, z))$

$$\partial_x u + \partial_z w = 0. \quad (3)$$

- Integrating (3) from z_b to z and using the kinematic condition at bottom ($w(x, z_b) = u(x)\partial_x z_b$) gives:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x). \quad (4)$$

Lagrangian Trajectories

- Incompressibility of the flow: $\nabla \cdot \mathbf{u} = 0$ with $\mathbf{u} = (u(x), w(x, z))$

$$\partial_x u + \partial_z w = 0. \quad (3)$$

- Integrating (3) from z_b to z and using the kinematic condition at bottom ($w(x, z_b) = u(x)\partial_x z_b$) gives:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x). \quad (4)$$

- The Lagrangian trajectory is characterized by the system

$$\begin{pmatrix} \dot{x}(t) \\ \dot{z}(t) \end{pmatrix} = \begin{pmatrix} u(x(t)) \\ w(x(t), z(t)) \end{pmatrix}. \quad (5)$$

Lagrangian Trajectories

- Incompressibility of the flow: $\nabla \cdot \mathbf{u} = 0$ with $\mathbf{u} = (u(x), w(x, z))$

$$\partial_x u + \partial_z w = 0. \quad (3)$$

- Integrating (3) from z_b to z and using the kinematic condition at bottom ($w(x, z_b) = u(x)\partial_x z_b$) gives:

$$w(x, z) = \left(\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z \right) u'(x). \quad (4)$$

- The Lagrangian trajectory is characterized by the system

$$\begin{pmatrix} \dot{x}(t) \\ \dot{z}(t) \end{pmatrix} = \begin{pmatrix} u(x(t)) \\ w(x(t), z(t)) \end{pmatrix}. \quad (5)$$

- A time-free reformulation for z as

$$z(x) = \eta(x) + \frac{u(0)}{u(x)} (z(0) - \eta(0)), \quad (6)$$

- The Beer-Lambert law describes how light is attenuated with depth:

$$I(x, z) = I_s \exp\left(-\varepsilon(\eta(x) - z)\right). \quad (7)$$

Here ε is the light extinction coefficient.

- The Beer-Lambert law describes how light is attenuated with depth:

$$I(x, z) = I_s \exp \left(- \varepsilon (\eta(x) - z) \right). \quad (7)$$

Here ε is the light extinction coefficient.

- Replacing z by (6):

$$I(x, z) = I_s \exp \left(- \varepsilon \frac{u(0)}{u(x)} (\eta(0) - z(0)) \right). \quad (8)$$

- The Beer-Lambert law describes how light is attenuated with depth:

$$I(x, z) = I_s \exp \left(- \varepsilon (\eta(x) - z) \right). \quad (7)$$

Here ε is the light extinction coefficient.

- Replacing z by (6):

$$I(x, z) = I_s \exp \left(- \varepsilon \frac{u(0)}{u(x)} (\eta(0) - z(0)) \right). \quad (8)$$

- For a given position $z(0) = \eta(0) - qh(0)$ with $q \in [0, 1]$, we have

$$I(x, z) = I_s \exp \left(- \varepsilon \frac{u(0)}{u(x)} qh(0) \right) = I_s \exp \left(- \varepsilon qh(x) \right)$$

- *A*: open and ready to harvest a photon,
B: closed while processing the absorbed photon energy,
C: inhibited if several photons have been absorbed simultaneously.

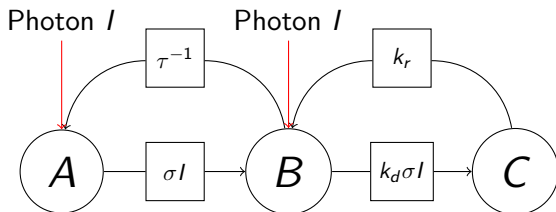


Figure: Scheme of the Han model, representing the probability of state transition, as a function of the photon flux density.

- A : open and ready to harvest a photon,
 B : closed while processing the absorbed photon energy,
 C : inhibited if several photons have been absorbed simultaneously.

-

$$\begin{cases} \dot{A} = -\sigma IA + \frac{B}{\tau}, \\ \dot{B} = \sigma IA - \frac{B}{\tau} + k_r C - k_d \sigma IB, \\ \dot{C} = -k_r C + k_d \sigma IB. \end{cases} \quad (9)$$

- A : open and ready to harvest a photon,
 B : closed while processing the absorbed photon energy,
 C : inhibited if several photons have been absorbed simultaneously.

-

$$\begin{cases} \dot{A} = -\sigma IA + \frac{B}{\tau}, \\ \dot{B} = \sigma IA - \frac{B}{\tau} + k_r C - k_d \sigma IB, \\ \dot{C} = -k_r C + k_d \sigma IB. \end{cases} \quad (9)$$

- A, B, C are the relative frequencies of the three possible states

$$A + B + C = 1.$$

- Using a fast-slow approximation and the singular perturbation theory(see [4]), this system can be reduced to one single evolution equation:

$$\dot{C} = -\alpha(I)C + \beta(I),$$

where

$$\alpha(I) = \beta(I) + k_r, \text{ with } \beta(I) = k_d \tau \frac{(\sigma I)^2}{\tau \sigma I + 1}.$$

- Using a fast-slow approximation and the singular perturbation theory(see [4]), this system can be reduced to one single evolution equation:

$$\dot{C} = -\alpha(I)C + \beta(I),$$

where

$$\alpha(I) = \beta(I) + k_r, \text{ with } \beta(I) = k_d \tau \frac{(\sigma I)^2}{\tau \sigma I + 1}.$$

- The net specific growth rate:

$$\mu(C, I) := -\gamma(I)C + \zeta(I),$$

where

$$\zeta(I) = \gamma(I) - R, \text{ with } \gamma(I) = \frac{k\sigma I}{\tau \sigma I + 1}.$$

- A time-free reformulation of C

$$C' = \frac{-\alpha(I)C + \beta(I)}{u}.$$

- A time-free reformulation of C

$$C' = \frac{-\alpha(I)C + \beta(I)}{u}.$$

- The average net specific growth rate over the domain is defined by

$$\bar{\mu} := \frac{1}{L} \int_0^L \frac{1}{h(x)} \int_{z_b(x)}^{\eta(x)} \mu(C(x, z), I(x, z)) dz dx.$$

- A time-free reformulation of C

$$C' = \frac{-\alpha(I)C + \beta(I)}{u}.$$

- The average net specific growth rate over the domain is defined by

$$\bar{\mu} := \frac{1}{L} \int_0^L \frac{1}{h(x)} \int_{z_b(x)}^{\eta(x)} \mu(C(x, z), I(x, z)) dz dx.$$

- In order to compute numerically, consider a uniform vertical discretization of the initial position $z(0)$ for N_z cells:

$$z_i(0) = \eta(0) - \frac{i - \frac{1}{2}}{N_z} h(0), \quad i = 1, \dots, N_z.$$

- A time-free reformulation of C

$$C' = \frac{-\alpha(I)C + \beta(I)}{u}.$$

- The average net specific growth rate over the domain is defined by

$$\bar{\mu} := \frac{1}{L} \int_0^L \frac{1}{h(x)} \int_{z_b(x)}^{\eta(x)} \mu(C(x, z), I(x, z)) dz dx.$$

- In order to compute numerically, consider a uniform vertical discretization of the initial position $z(0)$ for N_z cells:

$$z_i(0) = \eta(0) - \frac{i - \frac{1}{2}}{N_z} h(0), \quad i = 1, \dots, N_z.$$

- The semi-discrete average net specific growth rate:

$$\bar{\mu}_\Delta = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \mu(C_i(x), I_i(x)) dx. \quad (10)$$

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.
- An ideal rearrangement of trajectories: at each new lap, the algae at depth $z_i(0)$ are entirely transferred into the position $z_j(0)$ when passing through the mixing device.

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.
- An ideal rearrangement of trajectories: at each new lap, the algae at depth $z_i(0)$ are entirely transferred into the position $z_j(0)$ when passing through the mixing device.
- We denote by \mathcal{P} the set of permutation matrices of size $N_z \times N_z$ and by \mathfrak{S}_{N_z} the associated set of permutations of N_z elements.

Mixing device

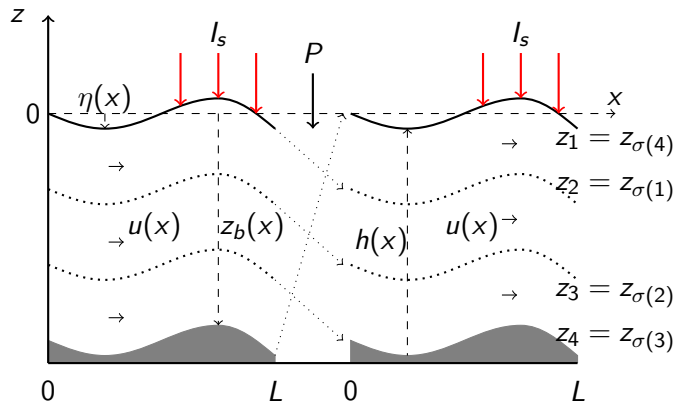


Figure: Representation of the hydrodynamic model with an example of mixing device (P). Here, P corresponds to the cyclic permutation $\sigma = (1\ 2\ 3\ 4)$.

Mixing device

- Paddle wheel:
 - set this hydrodynamic-biologic coupling system in motion,
 - modifies the elevation of the algae passing through it, and giving successively access to light to all the population.
- An ideal rearrangement of trajectories: at each new lap, the algae at depth $z_i(0)$ are entirely transferred into the position $z_j(0)$ when passing through the mixing device.
- We denote by \mathcal{P} the set of permutation matrices of size $N_z \times N_z$ and by \mathfrak{S}_{N_z} the associated set of permutations of N_z elements.

Theorem

The average growth rate of K laps equals to one lap (see [2]).

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem**
 - No permutation
 - With a mixing device
- 4 Numerical Experiments
- 5 Conclusion and Perspective

Optimization problem

- Our goal:
 - Topography z_b ,
 - Mixing strategy P .

Optimization problem

- Our goal:
 - Topography z_b ,
 - Mixing strategy P .
- Volume of the system

$$V = \int_0^L h(x) dx.$$

Optimization problem

- Our goal:
 - Topography z_b ,
 - Mixing strategy P .
- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.

Optimization problem

- Our goal:
 - Topography z_b ,
 - Mixing strategy P .
- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.
- For instance: a truncated Fourier series

$$h(x, a) = a_0 + \sum_{m=1}^M a_m \sin(2m\pi \frac{x}{L}), \quad (11)$$

Optimization problem

- Our goal:
 - Topography z_b ,
 - Mixing strategy P .
- Volume of the system

$$V = \int_0^L h(x) dx.$$

- Parameterize h by a vector $a := [a_1, \dots, a_M] \in \mathbb{R}^M$.
- For instance: a truncated Fourier series

$$h(x, a) = a_0 + \sum_{m=1}^M a_m \sin(2m\pi \frac{x}{L}), \quad (11)$$

- The computational chain:

$$a \rightarrow h \rightarrow u, z_b \rightarrow z \rightarrow I \rightarrow C \rightarrow \bar{\mu}_\Delta.$$

- Objective function:

$$\bar{\mu}_{\Delta}(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(l_i(a))C_i + \zeta(l_i(a))dx,$$

- Objective function:

$$\bar{\mu}_{\Delta}(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(l_i(a))C_i + \zeta(l_i(a))dx,$$

- Constraints:

$$C_i' + \frac{\alpha(l_i(a))}{u(a)} C_i = \frac{\beta(l_i(a))}{u(a)}. \quad (12)$$

- Objective function:

$$\bar{\mu}_{\Delta}(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(l_i(a))C_i + \zeta(l_i(a))dx,$$

- Constraints:

$$C_i' + \frac{\alpha(l_i(a))}{u(a)} C_i = \frac{\beta(l_i(a))}{u(a)}. \quad (12)$$

- The optimization problem reads:

Find a^ solving the maximization problem:*

$$\max_{a \in \mathbb{R}^N} \bar{\mu}_{\Delta}(a).$$

- Lagrangian:

$$\begin{aligned}\mathcal{L}(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(I_i(a))C_i + \zeta(I_i(a))dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \left(C_i' + \frac{\alpha(I_i(a))C_i - \beta(I_i(a))}{u(a)} \right) dx\end{aligned}$$

- Lagrangian:

$$\begin{aligned}\mathcal{L}(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(I_i(a))C_i + \zeta(I_i(a))dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \left(C_i' + \frac{\alpha(I_i(a))C_i - \beta(I_i(a))}{u(a)} \right) dx\end{aligned}$$

- p_i the Lagrange multipliers associated with the constraint (12).

$$\begin{cases} \partial_{C_i} \mathcal{L} = p_i' - p_i \frac{\alpha(I_i(a))}{u(a)} - \frac{1}{LN_z} \gamma(I_i(a)) \\ \partial_{C_i(L)} \mathcal{L} = p_i(L). \end{cases}$$

- Lagrangian:

$$\mathcal{L}(C, p, a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(I_i(a))C_i + \zeta(I_i(a))dx \\ - \sum_{i=1}^{N_z} \int_0^L p_i \left(C_i' + \frac{\alpha(I_i(a))C_i - \beta(I_i(a))}{u(a)} \right) dx$$

- p_i the Lagrange multipliers associated with the constraint (12).

$$\begin{cases} \partial_{C_i} \mathcal{L} = p_i' - p_i \frac{\alpha(I_i(a))}{u(a)} - \frac{1}{LN_z} \gamma(I_i(a)) \\ \partial_{C_i(L)} \mathcal{L} = p_i(L). \end{cases}$$

- If C is periodic (i.e. $C(0) = C(L)$), then $\partial_{C_i(L)} \mathcal{L} = p_i(L) - p_i(0)$.

No permutation

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

- where

$$\begin{aligned} \partial_a \mathcal{L} = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \left(-\gamma'(l_i(a))C_i + \zeta'(l_i(a)) \right) \partial_a l_i(a) dx \\ & + \sum_{i=1}^{N_z} \int_0^L p_i \frac{-\alpha'(l_i(a))C_i + \beta'(l_i(a))}{u(a)} \partial_a l_i(a) dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i \frac{-\alpha(l_i(a))C_i + \beta(l_i(a))}{u^2(a)} \partial_a u(a) dx. \end{aligned}$$

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

Theorem

Under the parameterization (11), if C is periodic, then $\nabla \bar{\mu}_\Delta(0) = 0$ (see [1]).

- The gradient $\nabla \bar{\mu}_\Delta(a)$ is obtained by

$$\nabla \bar{\mu}_\Delta(a) = \partial_a \mathcal{L},$$

Theorem

Under the parameterization (11), if C is periodic, then $\nabla \bar{\mu}_\Delta(0) = 0$ (see [1]).

- Numerically, the flat topography is the optimum.

- Objective function:

$$\bar{\mu}_{\Delta}^P(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(I_i(a)) C_i^P + \zeta(I_i(a)) dx,$$

With a mixing device

- Objective function:

$$\bar{\mu}_{\Delta}^P(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(l_i(a)) C_i^P + \zeta(l_i(a)) dx,$$

- Constraint:

$$\begin{cases} C_i^{P'} + \frac{\alpha(l_i(a))}{u(a)} C_i^P & = \frac{\beta(l_i(a))}{u(a)} \\ \color{red}{P} C^P(L) & = C^P(0). \end{cases} \quad (13)$$

- Objective function:

$$\bar{\mu}_{\Delta}^P(a) = \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(I_i(a)) C_i^P + \zeta(I_i(a)) dx,$$

- Constraint:

$$\begin{cases} C_i^{P'} + \frac{\alpha(I_i(a))}{u(a)} C_i^P & = \frac{\beta(I_i(a))}{u(a)} \\ \mathbf{P} C^P(L) & = C^P(0). \end{cases} \quad (13)$$

- Our optimization problem reads:

Find a permutation matrix P_{\max} and a parameter vector a^ solving the maximization problem:*

$$\max_{P \in \mathcal{P}} \max_{a \in \mathbb{R}^M} \bar{\mu}_{\Delta}^P(a).$$

- Lagrangian:

$$\begin{aligned}\mathcal{L}^P(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(l_i(a))C_i^P + \zeta(l_i(a))dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i^P \left(C_i^{P'} + \frac{\alpha(l_i(a))C_i^P - \beta(l_i(a))}{u(a)} \right) dx\end{aligned}$$

- Lagrangian:

$$\begin{aligned}\mathcal{L}^P(C, p, a) = & \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L -\gamma(l_i(a)) C_i^P + \zeta(l_i(a)) dx \\ & - \sum_{i=1}^{N_z} \int_0^L p_i^P \left(C_i^{P'} + \frac{\alpha(l_i(a)) C_i^P - \beta(l_i(a))}{u(a)} \right) dx\end{aligned}$$

- p_i^P is the Lagrange multiplier associated with the constraint (13).

$$\begin{cases} p_i^{P'} - p_i^P \frac{\alpha(l_i(a))}{u(a)} - \frac{1}{LN_z} \gamma(l_i(a)) & = 0 \\ p^P(L) - p^P(0) P & = 0. \end{cases}$$

With a mixing device

The gradient $\nabla \bar{\mu}_{\Delta}^P(a)$ is obtained from

$$\nabla \bar{\mu}_{\Delta}^P(a) = \partial_a \mathcal{L}^P,$$

where

$$\begin{aligned} \partial_a \mathcal{L}^P &= \frac{1}{LN_z} \sum_{i=1}^{N_z} \int_0^L \left(-\gamma'(l_i(a)) C_i^P + \zeta'(l_i(a)) \right) \partial_a l_i(a) dx \\ &\quad + \sum_{i=1}^{N_z} \int_0^L p_i^P \frac{-\alpha'(l_i(a)) C_i^P + \beta'(l_i(a))}{u(a)} \partial_a l_i(a) dx \\ &\quad - \sum_{i=1}^{N_z} \int_0^L p_i^P \frac{-\alpha(l_i(a)) C_i^P + \beta(l_i(a))}{u^2(a)} \partial_a u(a) dx. \end{aligned}$$

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem
- 4 Numerical Experiments**
 - Numerical Settings
 - Numerical results
- 5 Conclusion and Perspective

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc
- The spatial increment: $\Delta x = 0.01 \text{ m}$

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc
- The spatial increment: $\Delta x = 0.01 \text{ m}$
- Light intensity at free surface: $I_s = 2000 \mu\text{mol} \cdot \text{m}^{-2} \text{s}^{-1}$ (which corresponds to a maximum value during summer in the south of France).

Numerical Settings

- Numerical Algorithm: Gradient-based optimization algorithm, *fminunc*, *fmincon*, etc
- Numerical solvers: Euler Explicit, Heun, etc
- The spatial increment: $\Delta x = 0.01 \text{ m}$
- Light intensity at free surface: $I_s = 2000 \mu\text{mol} \cdot \text{m}^{-2} \text{s}^{-1}$ (which corresponds to a maximum value during summer in the south of France).
- Assume that only q percent of I_s is available at the bottom $q \in [0, 1]$

$$\varepsilon = (1/h(0, a)) \ln(1/q).$$

Parameter Settings

- Standard settings for a raceway pond
 - Length of one lap of the raceway $L = 100$ m
 - Averaged discharge $Q_0 = 0.04 \text{ m}^2 \cdot \text{s}^{-1}$
 - Initial position of the topography $z_b(0) = -0.4$ m
 - First Fourier coefficient $a_0(= h(0, a)) = 0.4$
- The free-fall acceleration is set to be $g = 9.81 \text{ m} \cdot \text{s}^{-2}$.

Parameter Settings

- Standard settings for a raceway pond
 - Length of one lap of the raceway $L = 100$ m
 - Averaged discharge $Q_0 = 0.04 \text{ m}^2 \cdot \text{s}^{-1}$
 - Initial position of the topography $z_b(0) = -0.4$ m
 - First Fourier coefficient $a_0 (= h(0, a)) = 0.4$
- The free-fall acceleration is set to be $g = 9.81 \text{ m} \cdot \text{s}^{-2}$.
- All the numerical parameters values for Han's model are taken from [3] and given in table 1.

Table: Parameter values for Han Model

k_r	$6.8 \cdot 10^{-3}$	s^{-1}
k_d	$2.99 \cdot 10^{-4}$	-
τ	0.25	s
σ	0.047	$\text{m}^2 \cdot (\mu \text{ mol})^{-1}$
k	$8.7 \cdot 10^{-6}$	-
R	$1.389 \cdot 10^{-7}$	s^{-1}

Convergence of N_z

For 100 random a chosen, the average value of the functional $\bar{\mu}_\Delta$

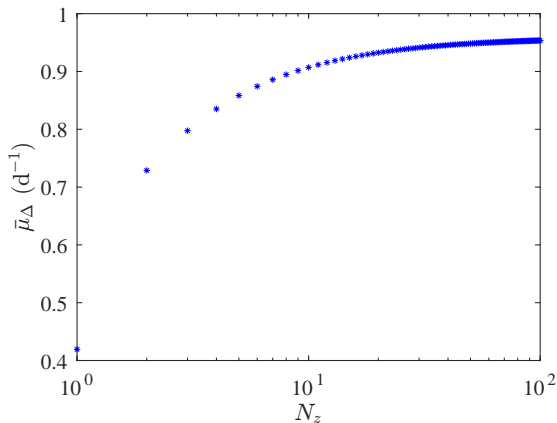


Figure: The value of the functional $\bar{\mu}_\Delta$ for $N_z = [1, 100]$.

C no periodic

The initial condition $C_0 = 0.1$

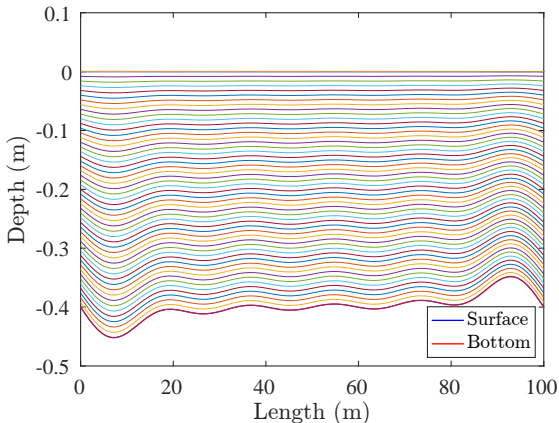


Figure: The optimal topography for $C_0 = 0.1$. The red thick line represents the topography (z_b), the blue thick line represents the free surface (η), and all the other curves between represent the different trajectories.

Optimal topography for a given permutation

The permutation: $\pi = (1 N_z)(2 N_z - 1)(3 N_z - 2) \cdots$,

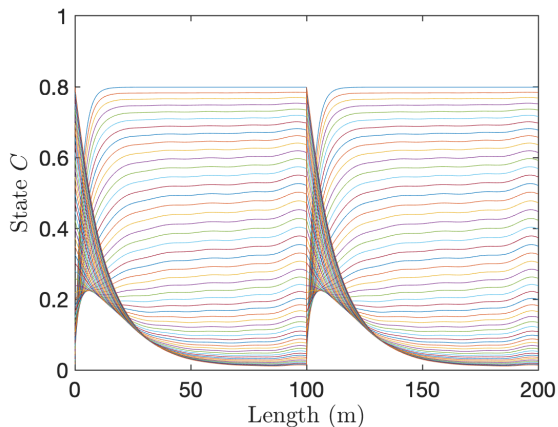
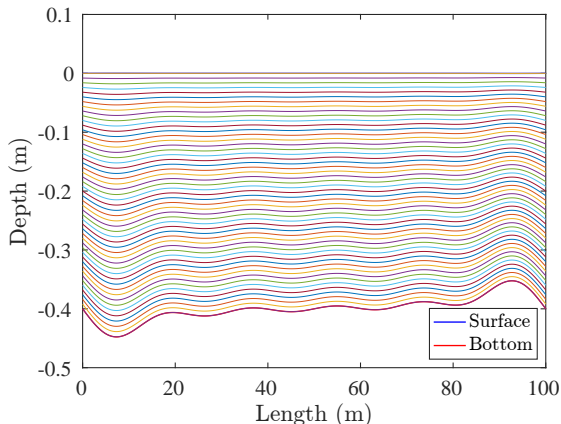


Figure: The evolution of the photo-inhibition state C for two laps.

Optimal topography for a given permutation

The permutation: $\pi = (1 N_z)(2 N_z - 1)(3 N_z - 2) \cdots$,



The increase in the optimal value of the objective function $\bar{\mu}_\Delta$ compared to a flat topography is around 0.228%, and compare to a flat topography and non permutation case is around 0.277%.

Optimal matrix and optimal topography

- Test $N_z!$ cases.

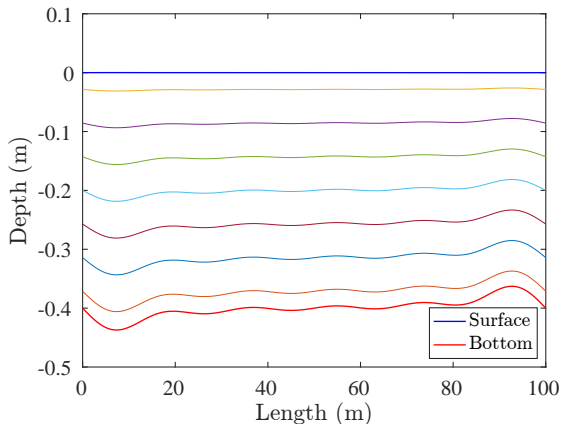
Optimal matrix and optimal topography

- Test $N_z!$ cases.
- Set $N_z = 7$, the optimal matrix:

$$P_{\max} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Optimal matrix and optimal topography

Set $N_z = 7$, the optimal topography:



Compare to a flat topography with this P_{\max} , we have a gain of 0.224%, and a gain of 1.511% compare to the case a flat topography without permutation (i.e. \mathcal{I}_{N_z}).

Overview

- 1 Introduction
- 2 Raceway Modeling
- 3 Optimization problem
- 4 Numerical Experiments
- 5 Conclusion and Perspective**

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one



- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution in the case C is periodic and no permutation
 - A non flat topography slightly enhances the average growth rate

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution in the case C is periodic and no permutation
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution in the case C is periodic and no permutation
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate
- Perspectives
 - More general matrix P

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution in the case C is periodic and no permutation
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate
- Perspectives
 - More general matrix P
 - What happens in the case torrential

- Theoretical results
 - A flat topography cancels the gradient of the objective function in the case C is periodic and no permutation
 - Periodicity in the permutation case is actually one
- Numerical results
 - Flat topography is optimal solution in the case C is periodic and no permutation
 - A non flat topography slightly enhances the average growth rate
 - No trivial permutation strategies can be found to enhance the average growth rate
- Perspectives
 - More general matrix P
 - What happens in the case torrential
 - An extra diffusion term in Shallow water equations or a Brownian in Lagrangian trajectories

-  Olivier Bernard, Liudi Lu, Jacques Sainte-Marie, and Julien Salomon. Shape optimization of a microalgal raceway to enhance productivity. Working paper or Preprint, November 2020.
-  Olivier Bernard, Liudi Lu, and Julien Salomon. Optimizing microalgal productivity in raceway ponds through a controlled mixing device. Working paper or Preprint, October 2020.
-  Jérôme Grenier, F. Lopes, Hubert Bonnefond, and Olivier Bernard. Worldwide perspectives of rotating algal biofilm up-scaling. Submitted, 2020.
-  Pierre-Olivier Lamare, Nina Aguillon, Jacques Sainte-Marie, Jérôme Grenier, Hubert Bonnefond, and Olivier Bernard. Gradient-based optimization of a rotating algal biofilm process. *Automatica*, 105:80–88, July 2019.
-  Victor Michel-Dansac, Christophe Berthon, Stéphane Clain, and Françoise Foucher.

A well-balanced scheme for the shallow-water equations with topography.

Computers and Mathematics with Applications, 72(3):586–593, August 2016.